

Non-Emptiness for UHATs Is EXPSPACE-Hard

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Problem Statement & Proof Roadmap

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Problem (Non-Emptiness for UHAT)

Given a UHAT T , decide if $L(T) \neq \emptyset$.

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Why is this interesting?

Non-emptiness is a minimal verification question. If even this is EXPSPACE-hard, then richer verification tasks such as equivalence, universality, or property checking should not be expected to be easy in full generality.

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Today we show one of the main results by Bergstraßer et al.¹:

Theorem

The non-emptiness problem for UHAT is EXPSPACE-hard.

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Theorem (2^n -tiling)

2^n -tiling problem (will be introduced) is EXPSPACE-complete².

²F. Schwarzentruber, "The Complexity of Tiling Problems," arXiv:1907.00102, 2019.

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2^n -tiling problems are polynomial time reducible to the non-emptiness problems for B-RASP programs.

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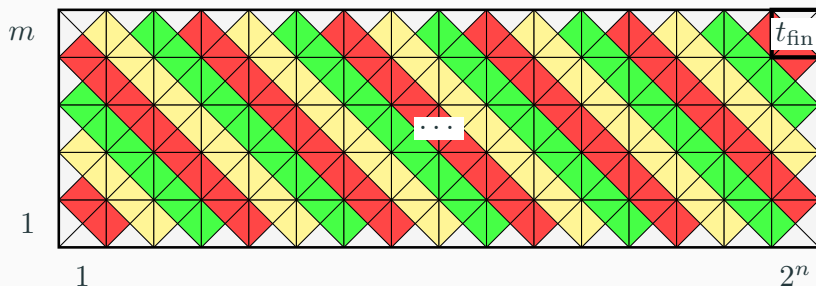
Theorem (A Lower Bound)

The non-emptiness problem for UHAT is EXPSPACE-hard.

$$2^n\text{-Tiling} \leq_p \text{B-RASP Non-Emptiness} \leq_p \text{UHAT Non-Emptiness}$$

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2^n -tiling Problem (EXPSPACE-complete!)

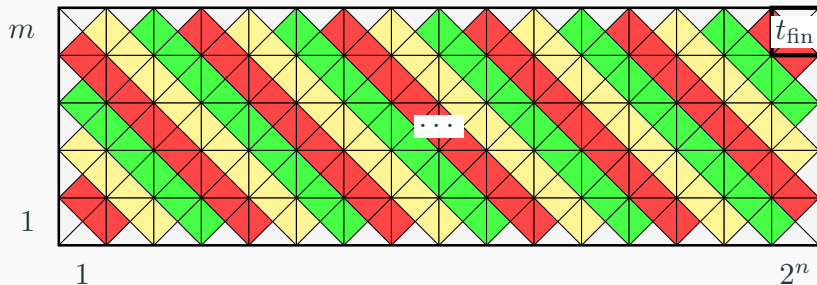


Definition (Tiles)

A *tile* is a quadruple $t \in \mathbb{N}_0^4$, where we write

$$t = \langle \text{left}(t), \text{up}(t), \text{right}(t), \text{down}(t) \rangle.$$

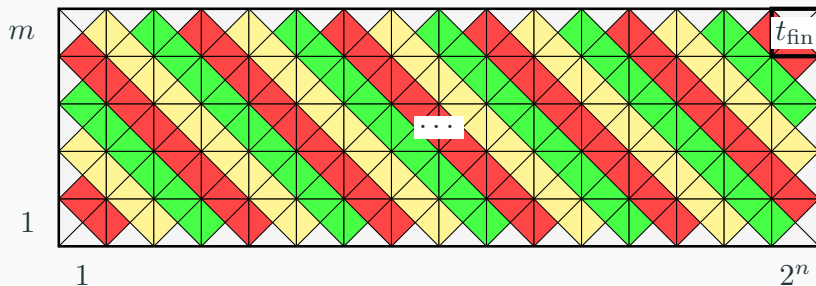
2^n -tiling Problem (EXPSPACE-complete!)



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Given (1) An integer $n > 0$ in unary, (2) a finite set T of tiles, and (3) a tile $t_{fin} \in T$,

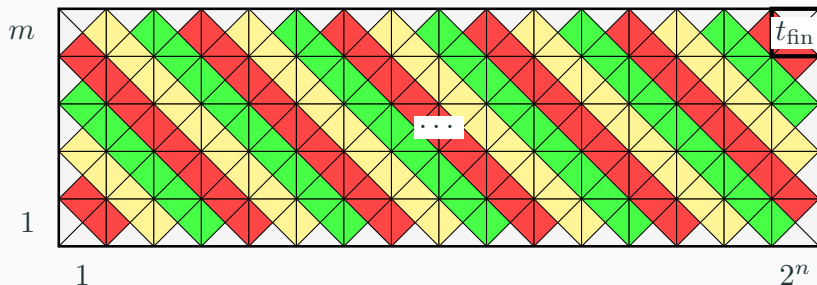
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Problem (2^n -tiling)

Given (1) An integer $n > 0$ in unary, (2) a finite set T of tiles, and (3) a tile $t_{fin} \in T$, *does there exist* an integer $m > 0$ and a function $\tau : \{1, \dots, 2^n\} \times \{1, \dots, m\} \rightarrow T$

2^n -tiling Problem (EXPSpace-complete!)



Problem (2^n -tiling)

Given (1) An integer $n > 0$ in unary, (2) a finite set T of tiles, and (3) a tile $t_{fin} \in T$, does there exist an integer $m > 0$ and a function $\tau : \{1, \dots, 2^n\} \times \{1, \dots, m\} \rightarrow T$ such that (1) $\tau(2^n, m) = t_{fin}$, (2) $\text{down}(\tau(i, 1)) = \text{up}(\tau(i, m)) = 0$ for all $1 \leq i \leq 2^n$, (3) $\text{left}(\tau(1, j)) = \text{right}(\tau(2^n, j)) = 0$ for all $1 \leq j \leq m$, (4) $\text{right}(\tau(i, j)) = \text{left}(\tau(i + 1, j))$ for all $1 \leq i < 2^n$ and $1 \leq j \leq m$, and (5) $\text{up}(\tau(i, j)) = \text{down}(\tau(i, j + 1))$ for all $1 \leq i \leq 2^n$ and $1 \leq j < m$.

$2^n\text{-tiling} \leq_p \text{B-RASP non-emptiness}$

Recap on B-RASP programs

Vectors P_i in Restricted Access Sequence Processing (RASP)

- A feature vector assigns one value to each position of the input.
- A Boolean vector can record whether some property is true at each position.
- $Q_a(i) = 1 \Leftrightarrow w(i) = a$.

	1	2	3	4	5
input w	a	b	b	a	c
$P_1(Q_a)$	1	0	0	1	0
$P_2(Q_b)$	0	1	1	0	0
$P_3(Q_c)$	0	0	0	0	1
P_4	0	1	0	0	0

P_4 : position i is the first b .

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Definition (Sketching B-RASP)

- A B-RASP program *builds* new features with basic token features $(Q_a, Q_b, \dots)$.
- One of the vectors is designated as the *output vector* deciding acceptance.

	1	2	3	4	5
input w	a	b	b	a	c
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Recap on B-RASP programs: Building Operations

Position-wise operation

$P_{t+1}(i) := R(i)$, where $R(i)$ is some Boolean combination of $\{P_1(i), \dots, P_t(i)\}$.

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Attention operation

An attention operation defines a new feature vector P_{t+1} by letting each position i look at one selected position j ,

$$P_{t+1}(i) := \triangleright_j [M(i, j), S(i, j)] V(i, j) : D(i),$$

where S, V, D are Boolean combinations of $\{P_1(i), \dots, P_t(i)\}$.

- $M(i, j)$ is the mask, saying which positions j are visible from i .
- $S(i, j)$ is the score predicate, saying which visible positions are relevant.
- $\triangleright_j$ means: choose the rightmost visible j such that $S(i, j) = 1$.
- If such a position j exists, set $P_{t+1}(i) := V(i, j)$. If no such position exists, use the default value: $P_{t+1}(i) := D(i)$.

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Encoding Scheme

1. Define $\text{enc}_\tau : \{1, \dots, 2^n\} \times \{1, \dots, m\} \rightarrow \Sigma^*$ by $\text{enc}_\tau(i, j) := \langle i - 1 \rangle \tau(i, j) \#$ for all $i \in [1, 2^n]$ and $j \in [1, m]$, where $\langle i - 1 \rangle$ denotes the binary encoding of $i - 1$.

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2. Define $\text{enc}(\tau) := \text{enc}_\tau(1, 1) \cdots \text{enc}_\tau(2^n, 1) \text{enc}_\tau(1, 2) \cdots \text{enc}_\tau(2^n, m)$.

Example

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We construct a B-RASP program that accepts $\text{enc}(\tau)$ iff τ satisfies the conditions.

The construction: form checking

Example

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We first check if the input is of the form $(\{0, 1\}^n T \#)^*$ by the following vectors.

$$A_T(i) := \blacktriangleright_j [j < i, 1] \bigvee_{t \in T} Q_t(j) : 0$$

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$$A(i) := \blacktriangleright_j [j < i, \neg A_{enc}(j)] 0 : A_{enc}(i).$$

Require $A(|enc(\tau)|) = 1$.

The construction: counter checking

Example

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$$C_1(i) := \blacktriangleright_j [j < i, Q_0(j) \vee Q_1(j)] Q_1(j) : 0$$

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Require $C(|enc(\tau)|) = 1$.

The construction: final tile checking

Example

$0000a_1\#0001a_2\#0010a_3\#\cdots\#1111a_{2^4}\#.$ ($n = 4$, $m = 1$ and $a_i \in T$ for $i \in [2^4].$)

The construction: final tile checking

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$$B_t(i) := \blacktriangleright_j \left[j < i, \bigvee_{t' \in T} Q_{t'}(j) \right] Q_t(j) : 0 \quad \text{for all } t \in T$$

The construction: final tile checking

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The construction: boundary checking (1)

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$$\left(\bigvee_{\substack{t \in T: \\ \text{up}(t)=0}} B_t(j) \right) \wedge \left(\bigvee_{\substack{t \in T: \\ \text{up}(t)=0}} B_t(i) \right) : 0$$

The construction: boundary checking (2)

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$$E_{\vdash}(i) := \left(\bigwedge_{k=1}^n \neg C_k(i) \right) \rightarrow \left(\bigvee_{\substack{t \in T: \\ \text{left}(t)=0}} B_t(i) \right)$$
$$E_{\dashv}(i) := \left(\bigwedge_{k=1}^n C_k(i) \right) \rightarrow \left(\bigvee_{\substack{t \in T: \\ \text{right}(t)=0}} B_t(i) \right)$$

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$$\begin{aligned} E(i) := & \blacktriangleright_j [j < i, Q_{\#}(j) \wedge \neg (E_{\perp}(j) \wedge E_{\vdash}(j) \wedge E_{\dashv}(j))] \\ & 0 : E_{\perp}(i) \wedge E_{\top}(i) \wedge E_{\vdash}(i) \wedge E_{\dashv}(i). \end{aligned}$$

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Require $E(|\text{enc}(\tau)|) = 1$.

The construction: adjacency checking

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$$M_{\downarrow}(i) := \blacktriangleright_j \left[j < i, Q_{\#}(j) \wedge \bigwedge_{k=1}^n C_k(i) \leftrightarrow C_k(j) \right] \bigvee_{\substack{t, t' \in T: \\ \text{down}(t) = \text{up}(t')}} B_t(i) \wedge B_{t'}(j) : 1$$

$$M_{\leftarrow}(i) := \blacktriangleright_j [j < i, Q_{\#}(j)] \left(\bigvee_{k=1}^n C_k(i) \right) \rightarrow \left(\bigvee_{\substack{t, t' \in T: \\ \text{left}(t) = \text{right}(t')}} B_t(i) \wedge B_{t'}(j) \right) : 1$$

$$M(i) := \blacktriangleright_j [j < i, Q_{\#}(j) \wedge \neg (M_{\downarrow}(j) \wedge M_{\leftarrow}(j))] 0 : M_{\downarrow}(i) \wedge M_{\leftarrow}(i).$$

Require $M(|\text{enc}(\tau)|) = 1$.

Definition (Acceptance of the B-RASP program)

1. The output vector is defined by the conjunction

$$Y(i) := A(i) \wedge C(i) \wedge F(i) \wedge E(i) \wedge M(i)$$

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- The B-RASP program recognizes the set of all $enc(\tau)$ where τ satisfies the conditions above.
- The language recognized by the B-RASP program is non-empty iff the 2^n -tiling problem has a solution.

The construction: wrap up

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Observations

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- The construction takes time polynomial in n .
- Why does this work?

Intuition

The B-RASP construction uses attention as an addressable lookup mechanism.

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Disk analogy: Can apply polynomial requirements on the disk addresses. The data on the disk would then need a DFA with exponential states to check.

Intuition & Comparison with real transformers

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**B-RASP non-emptiness $\leq_p$ UHAT
non-emptiness**

Lemma (B-RASP non-emptiness $\leq_p$ UHAT non-emptiness)

Given a B-RASP program $P_1, \dots, P_m$ where every attention operation is of the form

$$P_{t+1}(i) := \blacklozenge_j \left[M(i, j), S(j) \wedge \bigwedge_{k \in K} P_k(i) \leftrightarrow P_k(j) \right] V(i, j) : D(i),$$

where

- $|\Sigma| \leq t < m$,
- $\blacklozenge \in \{\blacktriangleleft, \blacktriangleright\}$,
- $S(j)$ is a Boolean combination of $\{P_1(j), \dots, P_t(j)\}$, and
- $K \subseteq \{1, \dots, t\}$,

one can construct in polynomial time a UHAT that recognizes the same language.

Recap on UHAT: Masked Unique Hard-Attention (UHA)

a_1 a_2 a_3 a_4 a_5 a_6 a_7

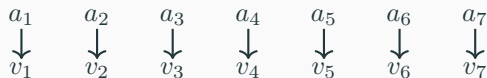
Definition (Sketching UHA)

- Input sequence $a_1 \cdots a_n \in \Sigma^n$.

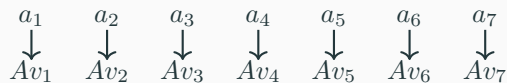
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$$\begin{array}{ccccccc} a_1 & a_2 & a_3 & a_4 & a_5 & a_6 & a_7 \\ \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow \\ Av_1 & Av_2 & Av_3 & Av_4 & Av_5 & Av_6 & Av_7 \end{array}$$

$$Bv_1$$

$$Bv_2$$

$$Bv_3$$

$$Bv_4$$

$$Bv_5$$

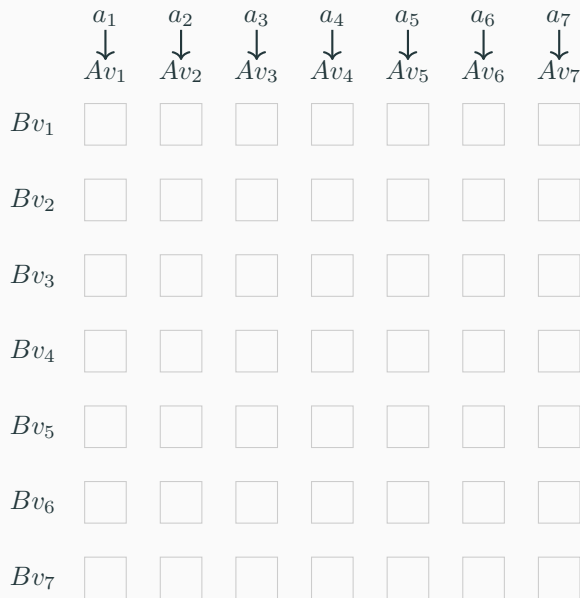
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	a_1 $\downarrow$ Av_1	a_2 $\downarrow$ Av_2	a_3 $\downarrow$ Av_3	a_4 $\downarrow$ Av_4	a_5 $\downarrow$ Av_5	a_6 $\downarrow$ Av_6	a_7 $\downarrow$ Av_7
Bv_1	☐	☐	☐	☐	☐	☐	☐
Bv_2	☒	☐	☐	☐	☐	☐	☐
Bv_3	☒	☒	☐	☐	☐	☐	☐
Bv_4	☒	☒	☒	☐	☐	☐	☐
Bv_5	☒	☒	☒	☒	☐	☐	☐
Bv_6	☒	☒	☒	☒	☒	☐	☐
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Bv_3	☒	☒	☐	☐	☐	☐	☐
Bv_4	☒	☒	☒	☐	☐	☐	☐
Bv_5	☒	☒	☒	☒	☐	☐	☐
Bv_6	☒	☒	☒	☒	☒	☐	☐
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Bv_1	☐	☐	☐	☒	☐	☐	☐
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Bv_3	☒	☒	☐	☒	☐	☐	☐
Bv_4	☒	☒	☒	☐	☐	☐	☐
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Bv_1							
Bv_2	×						
Bv_3	×	×		*			
Bv_4	×	×	×				
Bv_5	×	×	×	×			
Bv_6	×	×	×	×	×		
Bv_7	×	×	×	×	×	×	

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- Score $S(v_i, v_j) = \langle A(v_i), B(v_j) \rangle$.
- Tie Breaking τ . (why?)
- Value Update $C : \mathbb{Q}^{2r} \rightarrow \mathbb{Q}^s$.
For example, $v'_4 = C(v_3, v_4)$.

	a_1 $\downarrow$ Av_1	a_2 $\downarrow$ Av_2	a_3 $\downarrow$ Av_3	a_4 $\downarrow$ Av_4	a_5 $\downarrow$ Av_5	a_6 $\downarrow$ Av_6	a_7 $\downarrow$ Av_7
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Bv_3	☒	☒	☐	☒	☐	☐	☐
Bv_4	☒	☒	☒	☐	☐	☐	☐
Bv_5	☒	☒	☒	☒	☐	☐	☐
Bv_6	☒	☒	☒	☒	☒	☐	☐
Bv_7	☒	☒	☒	☒	☒	☒	☐

Recap on UHAT: ReLU, UHAT, and UHAT Acceptance

Definition (ReLU)

For each vector $v_i (i \in [n])$ and some k ,

$$\text{ReLU}(v_i) = (v_i[1, k-1], \max\{0, v_i(k)\}, v_i[k+1, n]).$$

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A *masked unique hard-attention transformer* (UHAT) is a length-preserving function $\mathcal{T} : \Sigma^+ \rightarrow (\mathbb{Q}^s)^+$ defined by application of a token embedding followed by application of a fixed sequence of UHA layers and ReLU layers of matching width.

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Definition (UHAT Acceptance)

Assume that $\mathcal{T}$ is given together with an *acceptance vector* $t \in \mathbb{Q}^s$. The recognized language $L(\mathcal{T})$ is then the set of words on which $\mathcal{T}$ outputs a sequence $v_1, \dots, v_n \in \mathbb{Q}^s$ with $\langle t, v_k \rangle > 0$, where $k \in [1, n]$ is either 1 or n depending on whether the first or last position is regarded the *output position* of $\mathcal{T}$.

B-RASP Program $\rightarrow$ UHAT: Embedding and Point-Wise Operation

Embedding

Each token $a \in \Sigma$ is embedded as a one hot vector according to Q_{a_i} 's.

	1	2	3	4	5
input w	a	b	b	a	c
$P_1(Q_a)$	1	0	0	1	0
$P_2(Q_b)$	0	1	1	0	0
$P_3(Q_c)$	0	0	0	0	1
P_4	0	1	0	0	0

P_4 : position i is the first b .

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Then we simulate the two operations: position-wise operation and attention operation.

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Point-wise operation

- Formally, for some Boolean combination R , we set $P_{t+1}(i) := R(P_1(i), \dots, P_t(i))$.
- In the B-RASP to UHAT translation, such Boolean combinations are simulated using affine transformations and ReLU layers.

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Simulating position-wise B-RASP operations

Bottom-up simulation needing only $\neg$ and $\wedge$

The UHAT simulates R bottom-up using affine maps and ReLU layers:

$$\neg x = 1 - x,$$

Simulating position-wise B-RASP operations

Bottom-up simulation needing only $\neg$ and $\wedge$

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$$\neg x = 1 - x,$$

and, for Boolean $x, y \in \{0, 1\}$,

$$x \wedge y = \max\{0, x + y - 1\}.$$

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Bottom-up simulation needing only $\neg$ and $\wedge$

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After computing the subformulas of R , the UHAT keeps only

$$(P_1(i), \dots, P_t(i), P_{t+1}(i)).$$

Attention Operations

$$P_{t+1}(i) := \blacktriangleright_j \left[M(i, j), S(j) \wedge \bigwedge_{k \in K} P_k(i) \leftrightarrow P_k(j) \right] V(i, j) : D(i),$$

or the analogous leftmost version.

Here: $M(i, j)$ is the mask, $S(j)$ is a Boolean condition on the candidate source position j , and

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Goal

Make UHAT hard attention select exactly the same j as the B-RASP operation.

Encoding the B-RASP score as a UHAT score

For each $k \in K$, the UHAT stores both

$$P_k(x) \quad \text{and} \quad 1 - P_k(x)$$

at every position x .

Use the attention score

$$\text{score}(i, j) = \sum_{k \in K} (P_k(i)P_k(j) + (1 - P_k(i))(1 - P_k(j))) - (1 - S(j)).$$

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For Boolean values,

$$P_k(i)P_k(j) + (1 - P_k(i))(1 - P_k(j)) = \begin{cases} 1, & P_k(i) = P_k(j), \\ 0, & P_k(i) \neq P_k(j). \end{cases}$$

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Hence

$$\text{score}(i, j) = |\{k \in K : P_k(i) = P_k(j)\}| - (1 - S(j)).$$

The maximum possible score is $|K|$, attained exactly when

$$S(j) = 1 \quad \text{and} \quad P_k(i) = P_k(j) \text{ for all } k \in K.$$

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Thus:

$$R(i) = 1 \quad \Rightarrow \quad P_{t+1}(i) = V(i, j_i),$$

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This exactly matches the B-RASP semantics.

The UHAT simulation maintains the invariant:

after simulating $P_1, \dots, P_t$, position i stores $(P_1(i), \dots, P_t(i))$.

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Acceptance

If P_t is the B-RASP output vector, stop constructing, and use acceptance one-hot vector e_t and the same output position k as P_t .

Then the UHAT accepts iff

$$\langle e_t, (P_1(k), \dots, P_t(k)) \rangle > 0.$$

Since all coordinates are Boolean, this is equivalent to $P_t(k) = 1$.

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Therefore the UHAT recognizes exactly the same language as the B-RASP program.

Questions?